# Rotational Position Transducer TEL: 0755-83376549 FAX: 0755-83376182 E-MAIL: szss208163.com

## DeviceNET® Ranges: 0-45° to 0-200 Turns Industrial Grade

## **Specification Summary:**

#### GENERAL

Full Stroke Ranges	0-0.125 to 0-200 turns
Electrial Interface	CANbus ISO 11898
Protocol	DeviceNet Version 2.0
Accuracy	see ordering information
Repeatability	± 0.02% full stroke
Resolution	
Enclosure Material powc	
Sensor	plastic-hybrid precision potentiometer
Shaft Loading	up to 10 lbs. radial and 5 lbs. axial
Starting Torque (25°C)	2.0 in-oz., max
Weight, Aluminum (Stainless Steel) Enclosur	e 3 lbs. (6 lbs.), max.

#### ELECTRICAL

Input Voltage	Bus Powered
Input Current	
Address Setting (Node ID)	063 set via DIP Switches—default setting: 63
Baud Rate	125K, 250K or 500K set via DIP Switches
EDS file	available @ http://www.celesco.com/download

#### **ENVIRONMENTAL**

Enviromental Suitability NEMA	4/4X/6, IP67/68
Operating Temperature	40° to 200°F
Vibration up to 10 G's to 200	)0 Hz maximum

## Outline Drawing



20630 Plummer Street • Chatsworth, CA 91311 tel: 800.423.5483 • +1.818.701.2750 • fax: +1.818.701.2799

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**RT8DN** 



Celesco's model RT8DN communicates rotational position feedback via DeviceNET® to your programmable controller. The heart of this sensor is a precision plastic-hybrid position potentiometer which provides a "absolute" position and does not ever have to be reset to a "home" position after a power loss or planned shutdown.

This innovative sensor from Celesco, designed to meet tough NEMA-4 and IP67 environmental standards, is available in full-stroke measurement ranges of 1/8 to 200 turns.

## **RT8DN** • Rotational Transducer: DeviceNET®





Data Field

#### \*Current Measurement Count

The Current Measurement Count (CMC) is the output data that indicates the present position of the measuring cable.

The CMC is a 16-bit value that occupies the first two bytes  $(B_0 \text{ and } B_1)$  of the data field.  $B_0$  is the LSB (least significant byte) and B<sub>1</sub> is the MSB (most significant byte).

The CMC starts at 0000H with shaft at the full counter-clockwise position (0° reference mark) and continues in the clockwise direction to the end of the stroke range stopping at FFFFH. This holds true for all ranges.

#### \*\*Full Stroke Range

The Full Stroke Range (FSR) is a 16-bit value in the data field that expresses the full range of the sensor in degrees. This value can be used to convert the actual count to units of measurement should the application require it.

The full stroke measurement range occupies the second two bytes  $(B_2 \text{ and } B_3)$  of the data field.

B<sub>2</sub> is the LSB (least significant byte) and B<sub>3</sub> is the MSB (most significant byte).

This value is expressed in degrees.

Example:

Hex Value	Decimal Equivalent	Full Stroke Range
0168	360	360 degrees

#### **Converting CMC to Degrees**

If required, the CMC can easily be converted to a rotational measurement expressed in degrees instead of counts.

This is accomplished by first dividing the CMC by 65,535 (total counts over the range) and then multiplying that value by the FSR:



Example:

If the full stroke range is 1 turn (360 degrees) and the current position is OFF2 Hex (4082 Decimal) then.



#### Address Setting (Node ID), Baud Rate and Bus Termination Settings

#### Address Setting (Node ID)

The Address Setting (Node ID) is set via 6 switches located on the 8-pole DIP switch found on the DeviceNET controller board located inside the transducer.

The DIP switch settings are binary starting with switch number  $1 (= 2^0)$  and ending with switch number  $6 (= 2^5)$ .

<b>DIP-1</b> (2 <sup>0</sup> )	<b>DIP-2</b> (2 <sup>1</sup> )	<b>DIP-3</b> (2 <sup>2</sup> )	<b>DIP-4</b> (2 <sup>3</sup> )	<b>DIP-5</b> (2 <sup>4</sup> )	<b>DIP-6</b> (2 <sup>5</sup> )	<i>address</i> (decimal)
0	0	0	0	0	0	0
1	0	0	0	0	0	1
0	1	0	0	0	0	2
•••	•••	•••	•••	•••	•••	•••
1	1	1	1	1	1	63
		"0"				



## **Baud Rate** The transmission baud rate may be either factory

preset at the time of order or set manually at the time of installation.

The baud rate can be set using switches 7 & 8 on the 8-pole DIP switch found on the DeviceNET controller board located inside the transducer.



#### **Bus Termination**

The setting of the internal bus termination resistor may be specified upon order or manually changed by the end user at the time of installation.

The bus termination resistor is activated setting switches 1 & 2 on the 2-pole DIP switch (located on the internal DeviceNET controller board) to the "ON" position.





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Ordering Information:

## Model Number:



Sa	Sample Model Number:										
R	T8DN - 100 - AL - 2	5 - FL - 500 - TR - SC5									
	range: enclosure: shaft: mounting style: baud rate: terminating resistor: electrical termination:	100 turns powder-painted aluminum .25-in diameter flange 500 k bits/sec. yes 5-meter cordset with straight plug									

## Full Stroke Range:

R order code:	R125	R25	R50	1	2	3	5	10	20
clockwise shaft rotations, min:	0.125	0.25	0.50	: 1	2	3	5	10	20
accuracy (% of f.s.):	1.25%	1.25%	0.5%	0.5%	0.5%	0.2%	0.2%	0.15%	0.15%
potentiometer cycle life*:	2.5 x 10 <sup>6</sup>	5 x 10 <sup>5</sup>	5 x 10 <sup>5</sup>	2.5 x 10 <sup>5</sup>	2.5 x 10 <sup>5</sup>				

<b>R</b> _order code:	30		40		50		80		100		120		140		180		200
clockwise shaft rotations, min:	30	:	40	:	50	:	80	:	100	:	120	:	140	:	180	:	200
accuracy (% of f.s.):	0.15%	÷	0.15%	:	0.15%	÷	0.15%	÷	0.15%	-	0.15%	:	0.15%	÷	0.15%		0.15%
potentiometer cycle life*:	2.5 x 10 <sup>5</sup>	:	2.5 x 10 <sup>5</sup>														

\*-number of times the sensor shaft can be cycled back and forth from beginning to end and back to the beginning before any measurable signal degradation may occur.

## **Enclosure Material:**

▲ order code:

AL powder-painted aluminum SS 303 stainless steel

## Shaft Diameter:



## Mounting Style:



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### Ordering Information:

## **Baud Rate:**



Terminating Resistor:

**b** order code:

TR terminating resistor NR no terminating resistor

## **Electrical Connection:**



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