Mounting Instructions

Inductive displacement transducer

WA..



B 25.WA.40 en

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Safety instructions

Use in accordance with the regulations

Displacement transducers of the WA type series are suitable for all situations where there are strict ruggedness and accuracy requirements, such as in research, development and industrial applications. Use for any additional purpose shall be deemed to be **not** in accordance with the regulations. In the interests of safety, the transducer should only be operated as described

in the Mounting Instructions. It is also essential to observe the appropriate legal and safety regulations for the application concerned during use. The same applies to the use of accessories.

The transducer is not a safety element within the meaning of its use as intended. Proper and safe operation of this transducer requires proper transportation, correct storage, assembly and mounting and careful operation and maintenance.

General dangers due to non-observance of the safety instructions

The WA displacement transducer corresponds to the state of the art and is fail-safe.

The transducers can give rise to residual dangers if they are inappropriately installed and operated by untrained personnel.

Everyone involved with the installation, commissioning, maintenance or repair of a displacement transducer must have read and understood the Mounting Instructions and in particular the technical safety instructions.

Residual dangers

The scope of supply and performance of the transducer covers only a small area of displacement measurement technique. In addition, equipment planners, installers and operators should plan, implement and respond to the safety engineering considerations of displacement measurement technique in such a way as to minimize residual dangers. Prevailing regulations must be complied with at all times. There must be reference to the residual dangers connected with displacement measurement technique. In these mounting instructions residual dangers are pointed out using the following symbols:

Symbol:

Symbol:

Symbol:



DANGER

Meaning:

Highest level of danger

Warns of a **directly** dangerous situation in which failure to comply with safety requirements **will** lead to death or serious physical injury.



WARNING

Meaning: Dangerous situation

Warns of a **potentially** dangerous situation in which failure to comply with safety requirements **can** lead to death or serious physical injury.



CAUTION

Meaning: Possibly dangerous situation

Warns of a potentially dangerous situation in which failure to comply with safety requirements **could** lead to damage to property, slight or moderate physical injury.



Refers to the fact that important information is being given about the product or its use.

Symbol:

Symbol:



Meaning: CE mark

The CE mark indicates a guarantee from the manufacturer that the product meets the requirements of the relevant EC directives (see Declaration of conformity on page 25).

Conversions and modifications

The transducer must not be modified from the design or safety engineering point of view except with our express agreement. Any modification shall exclude all liability on our part for any damage resulting therefrom.

Qualified personnel

This instrument is only to be installed by qualified personnel strictly in accordance with the technical data and with the safety rules and regulations which follow. It is also essential to observe the appropriate legal and safety regulations for the application concerned. The same applies to the use of accessories.

Qualified personnel means persons entrusted with the installation, fitting, commissioning and operation of the product who possess the appropriate qualifications for their function.

Accident prevention

The relevant accident prevention regulations of the trade safety associations must be taken into account.

1 Introduction

HBM's WA displacement transducers are particularly well suited for use with all applications requiring a high degree of durability and precision, such as research, development and industry.

To provide documentary evidence of quality, a separate test report containing the test data is included in the list of components supplied with the product.

2 Electrical structure and connection

The principle of measurement is based on an active quarter bridge (in the case of the WA2, on an active half bridge), that is expanded to a full bridge connection. The displacement transducer can be used in full-bridge and half-bridge mode. The transducer is designed with integral sensor circuits to operate in a six wire circuit.

When operating with a six wire amplifier, the cable can be shortened or lengthened (to a maximum of 300m) without effect, as the additional sensor circuits, gray and green, tap the voltage at the feeders in the sensor and carry it back to the six wire amplifier. This regulates the voltage so that it reaches the transducer loss-free.

2.1 Electrical connection WA electronics

The transducer is fitted with an integrated evaluation circuit for operating at direct voltage (15 – 30 volts). The integrated evaluation circuit is designed for operation with a separated extra-low voltage (SELV circuit). The WA electronics are not designed to be connected to a direct voltage network in accordance with EN 61010–1. The output signal is available as a standardized voltage value. The lower range value of the transducer corresponds to 0.5 V (live zero), the upper range value of the transducer corresponds to 10V. The cable connecting the WA electronics to follower electronics can be shortened or lengthened as required (max. 50m).



NOTE

For versions with a plug connection between the transducer and the electronics module, please note the following: **Transducer and electronics are assigned to each other and must not be interchanged.**

With cable extensions, use shielded cable (see Section 2.1 Pin assignment).

2.2 Pin assignment

| Transducer | Wire colour | Amp | lifier |
|------------------------|-------------------------|---------------------------|-----------------------|
| WA | Cable | 15-pin Sub-D connector | 7-pin MS-connector |
| Measurement signal (+) | WH = white | 8 | А |
| Measurement signal (-) | RD = red ¹⁾ | 15 | D |
| Excitation voltage (+) | BU = blue | 6 | С |
| Excitation voltage (-) | BK = black | 5 | В |
| Sensor circuit (+) | GN = green | 13 | F |
| Sensor circuit (-) | GY = gray ²⁾ | 12 | g |
| Shield | | Enclosure | Enclosure |

1) with full bridge only

²⁾ for the high temperature version: violet

2.3 Pin assignment WA electronics



Fig. 2.1: Electrical block diagram WA electronics

Special notes on operating WA transducers:



With amplifiers, you must connect zero operating voltage to the protection circuit (terminals):

in the case of system devices with a sliding switch (e.g. MGC), by connecting terminal 2 (zero operating voltage) to the protection circuit in the case of the MVD2555 amplifier.

Connecting to terminals:

- 1. The shield can be accessed through a notch in the cable sheath (see Fig. 2.2).
- 2. Place the shield flat on the body of the casing.

Fitting to a connector:

Place the cable shield flat on the connector housing (see chap. 6.1).



Fig. 2.2: Notched cable sheath

2.4 Principle of measurement, wiring assignment: WA2







Fig. 2.4: General electrical wiring-diagram, half bridge with 40mV/V

For information on using other transducer connection types, refer to the operating manual for the chosen amplifier (connection diagram WA, see types of connection).





2.5 Principle of meas., wiring assignment: WA10...WA500







Fig. 2.7: General electrical wiring-diagram, half bridge with 80mV/V



Fig. 2.8: General electrical wiring-diagram, half bridge with 10mV/V (optional) For information on using other transducer connection types, refer to the operating manual for the chosen amplifier (connection diagram WA, see types of connection).



Fig. 2.9: Lemosa connector pin assignment (solder side of male cable connector)

3 Balancing

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3.1 Zero balance

Plunger (WA/...-L)

The plunger has a threaded piece for connecting it to the measurement object.

- Insert the plunger into the transducer as far as the first marking ring (the projecting part of the plunger corresponds to size C, see page 18 "Dimensions").
- for the WA2: push in the core until the 0 (\pm 1mV/V) display
- for WA electronics: push in the core until the output voltage is 0.5V



The transducer and plunger must not be transposed.

The transducer and plunger are arranged by Ident. No. to prevent transposition. Plungers and coil systems that have not been balanced with one another can give rise to measurement errors in excess of 1%.



Fig.3.1: Plunger with markings (zero balance)

Probe (WA/...-T)

The mechanical zero position of the displacement probe (size E, see page 18 "Dimensions") is derived for neutral position with probe tip extended. With *WA electronics*, the output voltage here is 0.5 ± 0.05 V.

Movement of the probe tip in the measurement direction by an initial stroke of up to 0.5mm has no effect on the technical data of the displacement probe. Having chosen the position, any output signal still present should be reset to zero on the amplifier.

Initial stroke for the WA2 probe until $0 \pm 1 \text{mV/V}$ is reached on the amplifier. Initial stroke for WA electronics until 0.5 ± 0.05 V is reached on the amplifier.

3.2 Calibration

3.2.1 Coarse adjustment using marking rings on the plunger

By using the marking rings on the plunger, you can calibrate at an accuracy of ± 1 mm (not to be recommended for measurement "**längen**" ≤ 10 mm). The nominal displacement is derived by inserting the plunger as far as the last marking ring (100%) before the plunger thread (the projecting part of the plunger corresponds to size C minus size A, see "Dimensions" on page 18). With the plunger in this position, the output signal from the displacement transducer (nominal sensitivity 80mV/V ± 1 %) has to be assigned to a display or to an output signal from the amplifier.

With WA electronics the output signal of the displacement transducer in this end position is 10V ± 0.05 V.



Fig.3.2: Plunger with markings (sensitivity balancing)

3.2.2 Direct calibration

If a high degree of precision is required, we recommend direct calibration using gauge blocks with dimensions corresponding to the displacement, movement or change in length that you wish to measure. Use commercially available gauge blocks or templates for this purpose.

This ensures that the effect on tolerances of zero point, sensitivity, cable effects and amplifier sensitivity are compensated. This calibration must take the whole measurement chain into account.

For instance, when the position of the probe tip or plunger corresponds to the gauge block, the output signal from the displacement transducer (nominal sensitivity $80 \text{mV/V} \pm 1\%$) has to be assigned to a display or to an output signal from the amplifier.

3.2.3 Calibration with input of characteristics

The sensitivity of WA transducers using 80 mV/V has a characteristic tolerance of $\pm 1\%$ and can be input directly when using the conveniently designed amplifiers in the MGCplus, MVD2555 or PME series.



Please ensure that the sensitivity at an excitation voltage of $2.5 V_{\text{rms}}$ has been ascertained.

4 Hydraulic version

4.1 Instructions for mounting a piston

- 1. Bore out the piston from the cylinder.
- 2. Screw the plunger into the piston head and secure it with a lock-nut or adhesive.



Fig. 4.1: Piston (typical mounting)

4.2 Commissioning with HBM amplifiers

- 1. Draw out the transducer or the core until the zero position of the displacement transducer is reached (see dimension G, Page 18; differing for the WA2: ± 1 mV/V)
- 2. Carry out a zero balance.
- 3. Insert the transducer or the core until the nominal displacement of the transducer is reached
- 4. Balance the output signal to nominal displacement.

More notes on commissioning can be found in the appropriate operating manual for the selected amplifier.

5 Dynamic measurements

5.1 Frequency and acceleration limits

The measurement frequency range of the measurement chain has to be determined electrically from the upper cut-off frequency of the amplifier. You can find the appropriate data in the operating manual for your amplifier.

Maximum permissible acceleration has a decisive effect on the mechanical characteristics of the displacement transducer. This information can be found in the appendix to the Technical Data.

In the case of displacement probes, care must be taken that the probe pin does not withdraw from the measurement object due to inertia.

To a first approximation, many tasks may generally be regarded as sinusoidal. For maximum permitted acceleration a_{max} with given displacement amplitude s the mechanical cut-off frequency f_{max} is:

$$f_{zul} = \frac{1}{2\pi} \cdot \sqrt{\left(\frac{a_{zul}}{s}\right)}$$

6 Interference effects

Carrier frequency transmission is in principle highly insensitive to electrical interference. Even so, high-intensity interference can falsify measurements.

Interference can be injected into a measuring circuit from a source which is:

- electromagnetic,
- inductive
- galvanic
- mechanical.

Interference is most commonly caused by:

- high-power transmission lines running parallel to the measurement circuit,
- a nearby protection relay,
- electric motors,
- potential differences in the earth system or polyphase earthing of the measurement chain,
- potential differences caused by capacitive influences
- vibration,
- with amplifiers, you must connect zero operating voltage to the protection circuit (terminals).

6.1 Shielding design

The Greenline HBM shielding design ensures that the entire measurement chain is completely enclosed in a Faraday cage, due to the special way the cable shield is arranged (see also reprint G36.35.0, Greenline shielding design).

6.2 Signal ground

All devices – transducers, amplifiers and display devices – are located on an earth potential (if necessary wire to a potential equalization line). If this is not possible, the transducer should be fitted earth-isolated.

7 Dimensions

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| | | Displacement probe | | | | | | | | |
|--------------------|-----|--------------------|-----|-------|-------------|-----|----|-----|-----|-------|
| Measuring range | Α | В | С | D | g | ØH | J | Α | E | F |
| 02mm | 2 | 75.5 | 40 | 69 | 35.5 | 1.2 | 15 | 2 | 14 | 130 |
| 010mm | 10 | 66 | 40 | 69 | 26 ± 0.5 | 3.7 | 16 | 10 | 14 | 130 |
| 020mm | 20 | 87 | 55 | 84 | 32 ± 0.5 | 3.7 | 16 | 20 | 24 | 170 |
| 050mm | 50 | 117 | 85 | 114 | 32 ± 0.5 | 3.7 | 16 | 50 | 54 | 230 |
| 0100mm | 100 | 180 | 134 | 181.6 | 46 ± 10 | 3.7 | 16 | 100 | 104 | 372.6 |
| 0200mm | 200 | 280 | 234 | 281.6 | 46 ± 10 | 3.7 | 16 | | | |
| 0300mm | 300 | 380 | 334 | 381.6 | 46 ± 10 | 3.7 | 16 | | | |
| 0500mm | 500 | 580 | 534 | 581.6 | 46 ± 10 | 3.7 | 16 | | | |

8 Types of connection (mechanical)



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SUNSTAR自动化 http://www.sensor-ic.com/ TEL: 0755-83376489 FAX:0755-83376182 E-MAIL:szss20@163.com

9 Mounting set

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10 Dimensions WA electronics



11 Specifications

| Туре | | WA2 | WA10 | WA20 | WA50 | WA100 | WA200 | WA300 | WA500 | | | |
|---|------|-------------|------|------|----------------|--------------------------|-------|-------|-------|--|--|--|
| Nominal displacement | mm | 02 | 010 | 020 | 050 | 0100 | 0200 | 0300 | 0500 | | | |
| Nominal sensitivity | | | | | | 1 | | | | | | |
| Nominal output signal at nominal displacement with output unloaded | mV/V | | 80 | | | | | | | | | |
| Characteristic | | | | | | | | | | | | |
| tolerance | | | | | | | | | | | | |
| Deviation of sensitivity from nominal sensitivity | % | | ± 1 | | | | | | | | | |
| Zero point tolerance | | | | | | | | | | | | |
| with core in zero position | mV/V | ±1 ±8 | | | | | | | | | | |
| Linearity deviation | | | | | | | | | | | | |
| Greatest deviation between start and end point (including hysteresis by | | | | | | | | | | | | |
| reference to nominal sensitivity) | % | | | | $\leq \pm 0.2$ | $2 \text{ or } \leq \pm$ | 0.1 | | | | | |
| Nominal temperature range | °C | - 20 + 80 | | | | | | | | | | |
| Operating temperature range | | | | | | | | | | | | |
| Standard | °C | | | | -3 | 0+80 | | | | | | |
| Variant for high temp. | °C | | | | -40 |)+150 | | | | | | |
| Effect of temperature on zero signal in nominal temperature range per 10K, by reference to nominal sensitivity | % | | | | | | | | | | | |
| Effect of temperature on output signal in nominal temperature range per 10K, by reference to actual value | % | < ±0.1 | | | | | | | | | | |
| Input resistance | Ω | 100± 10% | | | | 350 ± 10 | % | | | | | |
| Output resistance | Ω | 570± 10% | | | | 680±10 | % | | | | | |

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| Туре | | WA2 | WA10 | WA20 | WA50 | WA100 | WA200 | WA300 | WA500 | | | |
|---|------------------|-----------------------|---------------|-----------|------|-------------|-------|-------|-------|--|--|--|
| Nominal excitation | | | 1 | 1 | | | J. | 1 | | | | |
| voltage | V _{rms} | | | | | 2.5 | | | | | | |
| Operating range of the excitation voltage | V _{rms} | | | | (| 0.510 | | | | | | |
| Carrier frequency, | | | | | | | | | | | | |
| Nominal range | kHz | | | | 4 | .8±1% | | | | | | |
| Operating range | kHz | | $4.8 \pm 8\%$ | | | | | | | | | |
| Weight | | | | | | | | | | | | |
| of transducer body | g | 54 | 56 | 57 | 68 | 104 | 147 | 190 | 276 | | | |
| of plunger | g | 4 | 6 | 7 | 9 | 13 | 20 | 28 | 42 | | | |
| Surface materials | _ | - | | | - | t-resistant | | | | | | |
| Impact resistance, | | | | | | | | | | | | |
| test severity level to DIN IEC68, Part 2-27; | | | | | | | | | | | | |
| IEC 68-2-27-1987 | | | | | | | | | | | | |
| Number of impacts | | | | | | | | | | | | |
| (per direction) | _ | | | | | 1000 | | | | | | |
| Impact acceleration | m/s ² | | 650 | | | | | | | | | |
| Impact duration Impact form | ms _ | 3 Half sine wave | | | | | | | | | | |
| Vibration resistance, | | | | | | | | | | | | |
| test severity level to | | | | | | | | | | | | |
| DIN IEC 68, Part 2-6, IEC 68-2–6-1982 | | | | | | | | | | | | |
| Frequency range | Hz | | | | | 5 to 65 | | | | | | |
| Vibration acceleration | m/s ² | | | | | 150 | | | | | | |
| Stress duration (per direction) | h | | | | | 0.5 | | | | | | |
| Max. number of stress cycles | | | | 10 millio | n | | | _ | | | | |
| Spring constant | N/mm | | 0.1 | 116 | | 0.063 | | _ | | | | |
| Spring force in zero position (for 1mm initial stroke) approx. | N | 2.4 2 - | | | | | | | | | | |
| Spring force in final position (=nominal displacement) approx. | N | 2.7 3.6 4.7 8.2 8.3 - | | | | | | | | | | |
| Max. permissible | | | | | | | | | | | | |
| probe tip acceleration approx. | m/s² | 170 140 95 45 – | | | | | | | | | | |
| Max. permissible plunger acceleration | m/s ² | 2500 | | | | | | | | | | |
| Probe tip cut-off | | | | | | | | | | | | |
| frequency for 1mm stroke approx. | Hz | 6 | 60 | 55 | 45 | 30 | | _ | | | | |
| Surve applox. | ΠZ | Ċ | 0 | 55 | 40 | 30 | | _ | | | | |

| Туре | | WA2 | WA10 | WA20 | WA50 | WA100 | WA200 | WA300 | WA500 | | |
|---|-----|--------------------------------------|------|------|------|-------|-------|-------|-------|--|--|
| Probe tip cut-off frequency at nominal displacement approx. | Hz | 1 | 18 | 10 | 5 | 3 | | _ | | | |
| Degree of protection acc. to EN 60 529 | | | | | | | | | | | |
| for transducer duct and core channel | _ | IP67 (depending on connection piece) | | | | | | | | | |
| Max. permissible pressure (increasing load) | bar | 350 | | | | | | | | | |
| Overload limit (to VDI/VDE 2600, Sheet 4) | bar | 450 | | | | | | | | | |
| Destructive range (to VDI/VDE 2600, Sheet 4) | bar | > 500 | | | | | | | | | |

11.1 Specifications WA electronics

| Туре | | WA | WA | WA | WA | WA | WA | WA |
|---|----|---|----|----|---------|----------|-----|-----|
| | | 10 | 20 | 50 | 100 | 200 | 300 | 500 |
| Nominal displacement | mm | 10 | 20 | 50 | 100 | 200 | 300 | 500 |
| Nominal output span | V | 9.5 (0.510) | | | | | | |
| Output span tolerance | % | | | | 0.5 | 5 | | |
| Linearity deviation | | | | | | | | |
| Greatest deviation between start and end point (including hysteresis by reference to nominal | % | | | | | 0 | | |
| sensitivity) | | | | | ±0. | | | |
| Nominal temperature range | °C | -20+60 | | | | | | |
| Operating temperature range | °C | -20+70 | | | | | | |
| Effect of temperature on zero signal in nominal temperature range per 10K, by reference to nominal sensitivity | % | $\leq \pm 0.2$; typically $< \pm 0.15$ | | | | | | |
| Effect of temperature on output signal in nominal temperature range per 10K, by reference to actual value | % | $\leq \pm 0.15$; typically $< \pm 0.1$ | | | | | | |
| Supply voltage | V | | | | 15 | 30 | | |
| Dependence on supply voltage, typically | % | | | | 0.0 | 3 | | |
| Burden in the output | kΩ | | | | ≥1 | 0 | | |
| Current consumption | mA | | | 45 | (typica | ally 26) |) | |
| Power yield max. | W | 1.5 | | | | | | |
| Cut-off frequency | Hz | 520 filter 4th order, Butterworth | | | | | h | |
| Dimensions of the electronics module | mm | | | 10 | 2 x 32 | x 13.5 | | |
| Cable length betw. transducer and electronics | m | | | | 32 | 20 | | |
| Cable length betw. electronics and evaluator | m | | | | 35 | 50 | | |

12 Replacement parts, accessories

- PVC cable as cable type S1, 3m, with Lemosa connector (2–9268.0675 for 80mV/V / 2–9268.0580 for 10mV/V)
- PVC cable as cable type S2, length as required (max. 300m, 2–9268.0676 for 80mV/V / max. 20m, 2-9268.0588 for 10mV/V)
- PTFE cable as cable type S3, 3m; with Lemosa connector (2–9268.0766 for 80mV/V; 2–9268.0768 for 10mV/V)
- PTFE cable as cable type S4, length as required; max. 20m (2–9268.0767 for 80mV/V; 2–9268.0769 for 10mV/V)
- Lemosa connector, detachable (6-pin, 3-3312.0126 for 80mV/V / 8-pin, 3-3312.0139 for 10mV/V)
- Lemosa jack, detachable (6-pin, 3-3312.0235 for 80mV/V / 8-pin, 3-3312.0140 for 10mV/V)
- Measurement insert with carbide ball (3-6061.0003)
- Mounting set WS/ZB12

13 Declaration of conformity





Notes on the CE mark

In addition to the information specified in this Operating Manual, the following points must be observed when commissioning the transducer:

- Transducers with unterminated cables are to be fitted with connectors to CE standard. In this event the shielding must be laid evenly over the whole area. If a different connection technique is used for the same transducers (such as to amplifiers) then a good EMC shield is to be provided in the wiring loom, the shielding again being laid over the full area.
- In the case of a Series K-WA with the 31L type of connection, the connecting section of the stranded wires must be shielded in accordance with CE requirements.
- In the case of a Series K-WA with 31S or 32S types of connection in linearity class 0.1%, the linearity deviation of 0.1% may be exceeded under the influence of electromagnetic fields.

Modifications reserved. All details describe our products in general form only. They are not to be understood as express warranty and do not constitute any liability whatsoever.

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