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# **3-Component Quartz Force Sensor**

Types 9027C, 9028C, 9026C4

# 24x24x12 mm, -8 ... 8 kN

Quartz force sensors are able to measure the three perpendicular components of a dynamic or quasistatic force in any direction.

- Precise measurement regardless of the acting point of the force
- Large useable frequency range
- Compact size
- · Rust free and sealed sensor case
- · Plug connection via robust multipole connector



The 3-component force sensor is mounted under preload between two mounting flanges. The quartz force sensor can therefore measure compression and tensile forces.

The force measurement of the sensor is based on the piezoe-lectric principle. The application of a force results in the quartz washers in the sensor (one for each of the force components to be measured) yielding a charge proportional to the force. This is picked off by built-in electrodes and transferred to the corresponding connector.

The contact faces of the sensor are covered with ceramic discs to facilitate ground-isolated mounting of the sensor. The straightforward and vibration-resistant design of the sensor produces a very rigid structure. The resulting high natural frequency makes highly dynamic force measurements possible over a large frequency range.

The cable connection of the sensors is made via a 3-pole connector V3 neg. (design patented). This is provided with a positioning aid for simple centering that also protects the plug and receptacle connector against unintended rotation.

After correct mounting the sensor is immediately ready for use without recalibration.

# **Application**

Kistler 3-component quartz force sensors measure simply, directly and precisely. They are used in the measurement of:

- Cutting forces in metal cutting processes
- · Collision forces in crash tests
- Recoil forces of rocket motors
- Vibration and friction forces
- Ground reaction forces in biomechanics
- · Vehicle forces on the road and test bed
- Forces on wind tunnel balances



# Technical Data Types 9027C, 9028C

| Pango                          | C C                             | kN   | -4 4              | 1)    |
|--------------------------------|---------------------------------|------|-------------------|-------|
| Range                          | F <sub>x</sub> , F <sub>y</sub> |      |                   | 1)    |
|                                | F <sub>z</sub>                  | kN   | -8 8              | 2)    |
|                                |                                 | kN   | 0 28              | 1)    |
| Overload                       | F <sub>x</sub> , F <sub>y</sub> | kN   | -5/5              |       |
|                                | $F_z$                           | kN   | -10/10            | 1)    |
| Calibrated range               | F <sub>x</sub>                  | kN   | 0 4               | 1)    |
|                                | F <sub>y</sub>                  | kN   | 0 4               | 1)    |
|                                | $F_z$                           | kN   | 0 8               | 1)    |
|                                | F <sub>z</sub>                  | kN   | 0 28              | 2)    |
| Permissible moment loading     | M <sub>x</sub> , M <sub>y</sub> | N∙m  | -22/22            | 1)    |
|                                | Mz                              | N∙m  | -23/23            | 1)    |
| Threshold                      |                                 | N    | <0,01             |       |
| Sensitivity                    | F <sub>x</sub> , F <sub>y</sub> | pC/N | ≈–7,8             | 1)    |
|                                | Fz                              | pC/N | ≈–3,8             | 1)    |
| Linearity, each axis           |                                 | %FSO | ≤±0,25            | 1)    |
| Hysteresis, each axis          |                                 | %FSO | ≤0,25             | 1)    |
| Crosstalk                      | $F_z \rightarrow F_x$ , $F_y$   | %    | ≤±0,5             | 1)    |
|                                | $F_x \leftrightarrow F_y$       | %    | ≤±2               | 1)    |
|                                | $F_x, F_y \rightarrow F_z$      | %    | ≤±3               | 1) 3) |
| Operating temperature range    |                                 | °C   | <b>-40</b> 1      | 20    |
| Insulation resistance at 20 °C |                                 | Ω    | >10 <sup>13</sup> |       |
| Ground isolation               |                                 | Ω    | >10 <sup>8</sup>  |       |
| Capacitance, each channel      |                                 | pF   | 30                |       |
| Connector                      |                                 |      | V3 neg.           |       |
| Weight                         |                                 | g    | 30                |       |
| Degree of Protection EN6052    | 29                              |      |                   |       |
| with cable Type 1698AA/AB      |                                 |      | IP65              |       |
| with cable Type 1698ACsp       |                                 |      | IP67              |       |
|                                |                                 |      |                   |       |

<sup>1)</sup> Standard mounting with 20 kN preload

2) Without preload

Page 1/4

This information corresponds to the current state of knowledge. Kistler reserves the right to make technical changes. Liability for consequential damage resulting from the use of Kistler products is excluded.

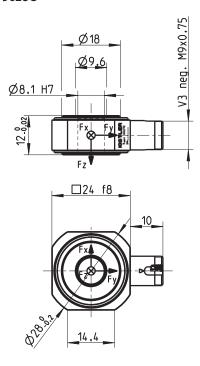
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 $<sup>^{3)}</sup>$  Crosstalk  $F_x,\,F_y\to F_z$  is  $\leq\!\pm2$  %, if e.g. four sensors are mounted in a dynamometer.

3-CcBUNGFAR传感/与控制:rh4rtp24/24ww/2 senser-iek/koliy/e=TE0270759283376549 FAX:0755-83376182E

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# Dimensions 3-Component Quartz Force Sensor Types 9027C, 9028C



Fi. 1: Dimensions Types 9027C, 9028C

#### **Sensor Variants**

# Type 9027C and 9028C

Type 9027C and 9028C sensors differ only in the position of the connector in relation to the coordinate system (see Fig. 2). The technical data of both types are identical.

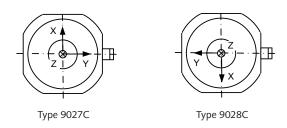


Fig. 2: 3-Component quartz force sensors Types 9027C and 9028C

# Type 9026C4

#### Set of four selected 3-component force sensors

The Type 9026C4 set consists of two selected sensors of Types 9027C and 9048C. The force sensors are all ground to the same height and are mounted in multicomponent dynamometers and measuring platforms.

The connectors of the four sensors all point inwards (see Fig. 3). The four force sensors are selected so that when they are mounted in a dynamometer they exhibit the best possible specifications in terms of constant sensitivity and minimum crosstalk.

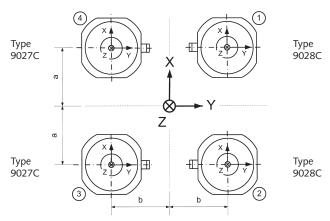


Fig. 3: Set of four selected 3-component force sensors Type 9026C4

# Mounting

The force sensor must be mounted under preload. The shear forces F<sub>x</sub> and F<sub>y</sub> are transferred from the base and cover plate to the surface of the sensor through static friction.

The measurement ranges shown in the technical data apply to the standard preload.

The precise sensitivity of the preloaded sensor must be established by on-site calibration.

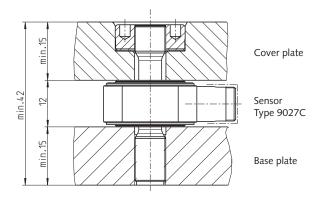


Fig. 4: Sensor mounting with standard preload

Page 2/4

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# Measuring System with 3-Component Quartz Force Sensor

| 3-Comp. quartz force sensor with V3 neg. connector | Degree of protection<br>EN60529 | Connecting cable <sup>1)</sup> | Multichannel<br>Charge amplifier <sup>2)</sup> | Meas.<br>value |
|--|---------------------------------|--------------------------------|--|----------------|
| Type 9027C, 9028C                                  |                                 | Туре 1698АА                    | Type 5070Ax00xx                                |                |
| V3 neg.  | IP65                            |                                |  |                |
|  |                                 | V3 pos. 3 x BNC pos.           |  |                |
|  |                                 | Type 1698AB                    | Type 5070Ax01xx                                | F <sub>x</sub> |
|  |                                 |                                |  | F <sub>y</sub> |
|  |                                 | V3 pos. Fischer 9 pole pos.    | S  |                |
|  |                                 | Type 1698ACsp                  |  |                |
|  | IP67  Cable welded to sensor    |                                |  |                |
|  |                                 | V3 pos. Fischer 9 pole pos.    |  |                |

# Measuring System with four 3-Component Quartz Force Sensor (Dynamometer)

| 3-Comp. quartz force sensor, V3 neg. conn. | Degr. of prot.<br>EN60529 | Connecting cable <sup>1)</sup> | Summing box  | Conn. cable <sup>1)</sup> | Multichannel<br>charge amplifier <sup>2)</sup> | Meas.<br>value   |
|--|---------------------------|--------------------------------|--|---------------------------|--|--|
| Type 9026C4                                |                           | Туре 1698АВ                    | Type 5417  | Туре 1687В                | Type 5070Ax01xx                                |  |
|  |                           | 4 pieces                       | IP65   | 3-core                    |  | Fx   |
|  | IP65                      |                                |  | pos. pos.                 | . 0  | F <sub>y</sub><br>F <sub>z</sub>   |
| ×  |                           | V3 pos. Fischer 9 pole pos.    | 100 Managare 100 M |                           | <u> </u>                                       |  |
| z  |                           | Type 1698ACsp                  |  | Туре 1677А                | Type 5070Ax11xx                                | F <sub>x12</sub>   |
|  |                           | 4 pieces                       | 148x62x35 mm   | 8-core                    | ***************************************        | F <sub>x34</sub><br>F <sub>y14</sub>                                       |
| 4 x V3 neg.                                | IP67                      |                                | 4 x Fischer Fischer Flange<br>9 pole neg. 9 pole neg.  |                           | . O  | F <sub>y23</sub><br>F <sub>z1</sub><br>F <sub>z2</sub><br>F <sub>z3</sub>  |
|  | Cable                     |                                | a bere medi.   |                           | Type 5070Ax21xx                                | F <sub>z4</sub>  |
|  | welded to<br>sensor       | V3 pos. Fischer 9 pole pos     |  | pos. pos.                 |  | F <sub>x</sub>   |
|  |                           |                                |  |                           | . 0  | F <sub>y</sub><br>Fz<br>M <sub>x</sub><br>M <sub>y</sub><br>M <sub>z</sub> |
|  |                           |                                |  |                           |  | IVIZ   |

<sup>1)</sup> see Cables for multicomponent force sensors, dynamometer and measuring platforms data sheet 1687B\_000-545.

Page 3/4

<sup>&</sup>lt;sup>2)</sup> see Multichannel charge amplifier for multicomponent force measurement data sheet 5070A\_000-485.

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# Set Preloading Elements M8x1

(see data sheet 9461\_000-197)



Fig 5: Set preloading elements Type 9461

# 3-Component Quartz Force Link

(see data sheet 9327C\_000-725)

Type 9027C force sensor is also available premounted as a calibrated quartz force link.



Fig. 6: Quartz force link Type 9327C

# **Paralleling**

When building a dynamometer, the four quartz force links are mechanically paralleled. The measuring signals (electric charge) of the four sensors can also be paralleled (summated). The summated signal corresponds to the algebraic total of the individual forces.

Type 5417 summing box facilitates the simple and reliable interconnection of measuring signals.



Fig 7: Summing box Type 5417

# Measuring Signal Processing

For the measuring system a charge amplifier is needed. This converts the measuring signal (charge) into a voltage. The value that is output is exactly proportional to the force.

Type 5070A multichannel charge amplifier was built specifically for the multicomponent force measuring system.



Fig. 8: Multichannel charge amplifier Type 5070A...

There is also Type 5080A... charge amplifier. This provides an extended measuring range and a higher degree of accuracy, particularly when measuring low forces.



Fig. 9: Multichannel charge amplifier Type 5080A...

#### **Included Accessories**

• None

Set of preloading elements has to be ordered seperately.

| Optional Accessories                              | Туре                 |
|---|----------------------|
| <ul> <li>Set preloading elements, M8x1</li> </ul> | 9461/                |
|   | 9461sp               |
| <ul> <li>Wrench adapter for Type 9461</li> </ul>  | 9475                 |
| <ul> <li>Connecting cable, 3-core</li> </ul>      | 1698AA <sup>1)</sup> |
| <ul> <li>Connecting cable, 3-core</li> </ul>      | 1698AB <sup>1)</sup> |
| Connecting cable, 3-core                          | 1698ACsp 1)          |
| Summing box                                       | 5417                 |
| Ordering Key                                      | Туре                 |
| 3-Component quartz force sensor                   | 9027C                |
| 24x24x12 mm, –8 8 kN                              |                      |
| 3-Component quartz force sensor                   | 9028C                |
| 24x24x12 mm, –8 8 kN                              |                      |
| (Connector turned)                                |                      |

| Set of four chosen               | 9026C4 |
|----------------------------------|--------|
| 3-Component quartz force sensors |        |
| 2 x Type 9027C, 2 x Type 9028C   |        |
| ground together                  |        |

technical measurements and minimum bending radii are to be taken from data sheet 1687B\_000-545

Page 4/4

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