

Torque Measuring Flange

Type 4510B...

Dual-Range Sensor, Assembly with Clamping Set

Torque measuring flanges Type 4510B... measure torque by strain gages. The digital measuring values are transmitted contactless from rotor to stator. There are analog and digital output signals available for evaluation.

- Rated torque: 100 ... 4 000 N·m
- Ratio for second range: 1:10 or 1:5 of rated torque
- Speed ranges up to 12 000 1/min
- Accuracy class in standard measuring range: 0,2
In the extended measuring range: 0,4
- Integral speed sensor with 60 pulses/revolution
- Maintenance-free, bearingless
- Flange and hub solution
- Digital non-contact signal transmission
- Electrical control signal
- Active temperature compensation
- Calibrated RS-232C output

Options

- Two separately calibrated measuring ranges 1:5 and 1:10
- Frequency output

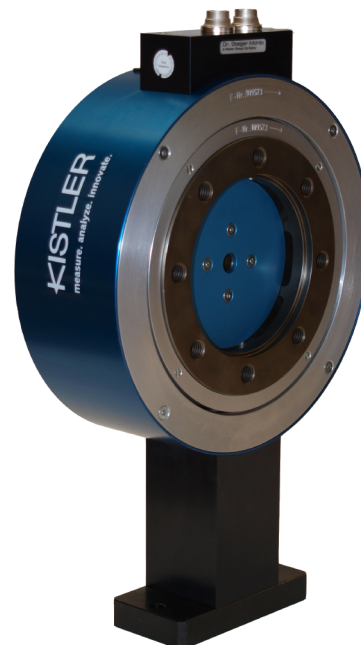
Description

Due to the design with clamp set the measuring flange may be mounted directly on the shaft of the infeed drive. The clamping set is in the scope of delivery. Adaption on the measuring side is done by means of a flange. Measuring flanges Type 4510B... are very robust and extensively unsensitive to bending moment and transverse forces.

The optional dual range version is predestinated for applications with high peak torque and medium average operating torque. A single range torque sensor should be selected for withstanding the peak torque. For measuring the average operating torque it would therefore be oversized.

Application

- Gear box test rigs
- Wheel load simulation
- Engine test rigs



General Electrical Specifications

Output signal option B1	VDC	±0 ... 10
at M _{nom} (rated value)	VDC	10
Output signal option B2	kHz	100±40
at M _{nom} (rated value)	kHz	140 (40)
Load resistance	kΩ	>10
Limit frequency –3 dB	kHz	1
100 % control input	VDC	"On" 3,5 ... 30 "Off" 0 ... 2
Control signal	% FSO	100± 0,1
Supply voltage	VDC	11 ... 30
Power consumption	W	<5

Electrical Measuring Data

Zero point stability (for 24 h)	% FSO	0,03
Reference temperature	°C	22 ±2
Operating temperature range (Rated temperature range)	°C	10 ... 60
Service temperature range	°C	0 ... 70
Storage temperature range	°C	–25 ... 80

Technical Data

Mechanical Basic Data

Type 4510B...			100	200	500	1K2	1K3	2K	4K
Rated torque	M_{nom}	N·m	100	200	500	1 000	1 000	2 000	4 000
Measuring range		N·m	100	200	500	1 000	1 000	2 000	4 000
Max. load clamping set		N·m	570	570	2 400	2 400	4 060	4 060	10 400
Limiting torque	M_{lp}	N·m	265	400	1 300	1 800	1 800	3 000	7 500
Rupture torque	M_{rupt}	N·m	>400	>800	>2 000	>4 000	>4 000	>8 000	>16 000
Alternating torque	M_{dyn}	N·m	100	200	500	1 000	1 000	2 000	4 000
Nominal speed	n_{nom}	1/min	12 000	12 000	9 000	9 000	9 000	9 000	9 000
Torsional rigidity	C_T	kN·m/rad	125	290	417	1 316	1 587	2 597	5 333
Rotation angle at M_{nom}	φ	°	0,046	0,04	0,069	0,044	0,036	0,044	0,043
Max. bending torque	M_b	N·m	1 600	1 600	1 700	1 700	5 000	5 000	8 500
Longitudinal force	F_A	kN	22	20	54	78	116	84	212
Max. radial force	F_Q	kN	3	3	8	8	12	15	20
Rotor weight	m_{rotor}	kg	4,4	4,4	7,7	7,8	10	10	12
Stator weight	m_{stator}	kg	3,6	3,6	4,4	4,4	4,4	4,4	4,4
Moment of inertia (rotor)	j_{rotor}	kg·m ² ·10 ⁻³	11,4	11,5	31	31,2	39,3	39,4	55,3
Partial mass of the rotor (measurement side)	$m_{rotor-M}$	kg	2,2	2,2	2,9	2,9	3,7	3,7	3,8
Partial moment of inertia of the rotor (measurement side)	$j_{rotor-M}$	kg·m ² ·10 ⁻³	8,2	8,2	20,1	20,2	21,8	21,8	21,9
Balancing class	Q		6,3						
Housing material			Hard anodized aluminum						
Protection class			IP54						

Electrical Measuring Data – Standard Measuring Range 1:1

Rated torque	N·m	100 ... 4 000
Accuracy class		0,2
Linearity error including hysteresis	%FSO	<±0,1
Temp. influence on the zero point	%FSO/10 °C	<±0,2
Temp. influence on the nominal value	%FSO/10 °C	<±0,2

Electrical Measuring Data – Extended Measuring Range 1:5, 1:10 (Option A1, A2)

Rated torque	N·m	100 ... 4 000
Accuracy class		0,4
Linearity error including hysteresis	%FSO	<±0,2
Temp. influence on the zero point	%FSO/10 °C	<±0,4
Temp. influence on the nominal value	%FSO/10 °C	<±0,4

Electrical Measuring Data – Speed

Pulses/revolution	1x60
Output signal	V 5 (TTL)

Dimensions

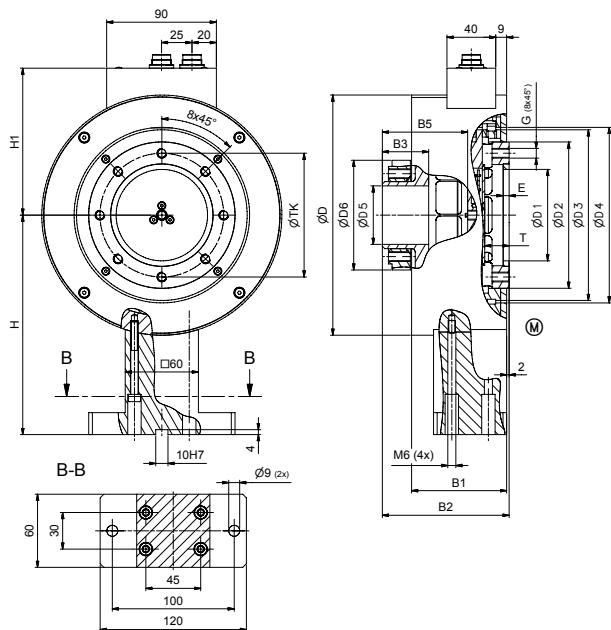


Fig. 1: Type 4510B... size 1 and 3

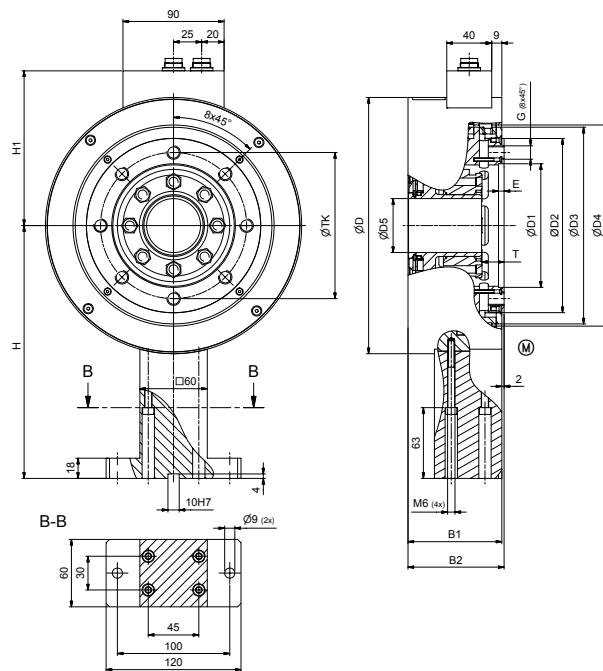


Fig. 2: Type 4510B... size 2

(M) = Measuring end

Dimensions in mm

Size	Measuring range N·m	øD	øD1 H7	øD2	øD3	øD4	øD5 G5	øD6	B1	B2	B4	B5	T	E	TKø	G	H	H1
1	100	197	75	120	140	144	48	90	78	104	68	70	20	5	101,5	M8	180	120,5
1	200	197	75	120	140	144	48	90	78	104	68	70	20	5	101,5	M8	180	120,5
2	500	228	110	155	175	179	48	—	83,5	85,5	—	—	20	5	130	M12	225	137,7
2	1 000	228	110	155	175	179	48	—	83,5	85,5	—	—	20	5	130	M12	225	137,7
3	1 000	228	110	155	175	179	65	141	83,5	123	86	88	19	5	130	M12	225	137,7
3	2 000	228	110	155	175	179	65	141	83,5	123	86	88	19	5	130	M12	225	137,7
3	4 000	228	110	155	175	179	80	170	83,5	132	93	95	19	5	130	M12	225	137,7

Electrical Connections

Pin Allocation of the 12-Pin Built-in Standard Connector A

Function	PIN	Description	
Supply	F	+U _B 11 ... 30 VDC, power consumption <5 W	
	A	Ground relating to +U _B	
Shield	M	In sensor connected to housing	
Torque output	C	Voltage output B1 ± 10 VDC bei $\pm M_{\text{Nom}}$ at >2 k Ω 10 VDC at control signal activation $R_{i,C} = 10 \Omega$, output short circuit	Frequency B2 F_{A+} frequency signal 5 V (TTL)
	D	AGND	Ground relating to U _A AGND frequency signal
Speed pulses	H	Track A	Active, TTL-level
	G		Not connected
	J		Not connected
100 % Control input	K	Control	Off: 0 ... 2 VDC On: 3,5 ... 30 VDC $R_{i,K} = 10$ k Ω
RS-232C interface to the CoMo Torque	B	TXD	Serial send path of the torque sensor
	L	RXD	Serial receive path of the torque sensor
Digital ground	E	DGND	Ground relating to speed pulses, calibration/control input, RS-232C interface

Pin Allocation of the 7-Pin Built-in Standard Connector B

Function	PIN	Description
Measuring range selection	1	Gain Normal (1:1) with 0 ... 2 VDC Extended (1:5 / 1:10) with 3,5 ... 30 VDC
—	2	For company internal functions, don't use!
Digital mass potential	3	DGND Ground relating to RS-232C interface
100 % control input	4	Control Off: 0 ... 2 VDC On: 3,5 ... 30 VDC
RS-232C interface	5	TXD Serial send path of the torque sensor
	6	RXD Serial receive path of the torque sensor
	7	OGND Ground relating for control

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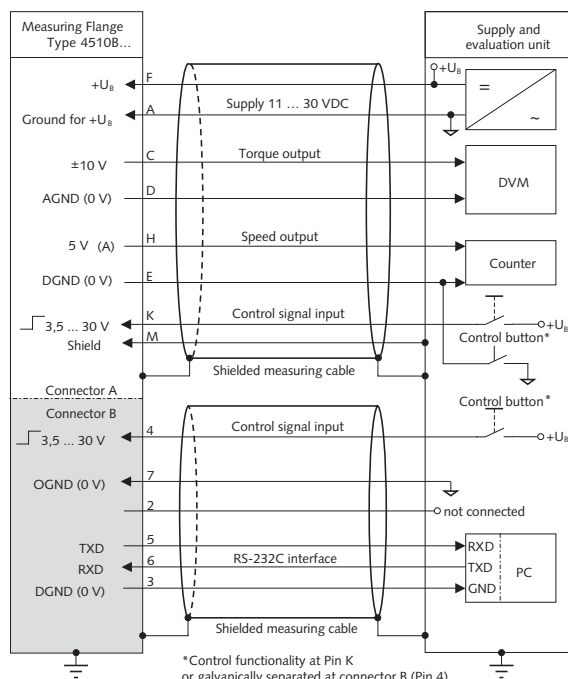


Fig. 4: Pin allocation of the built-in connector A and B (standard)

Mounting

Connection of Rotor, Fastening Bolts

Nominal torque M_{nom}	N·m	100	200	500	1 000 1K2	1 000 1 K3	2 000	4 000
Size		BG 1		BG 2		BG 3		
Thread		M8	M8	M12	M12	M12	M12	M12
Quality class		8.8	8.8	8.8	8.8	8.8	12.9	12.9
Min. mounting depth	mm	6	8	13	13	13	16	16
Max. mounting depth	mm	20	20	20	20	20	20	20
Fastening torque MA_{mz} – Flange	N·m	23	23	80	80	80	137	137
Fastening torque clamping set	N·m	12	12	35	35	58	58	70
Balancing class	Q	6,3						
Counterflange flatness	mm	0,01						
Counterflange concentricity	mm	0,02						
Max. offset rotor to stator:								
Axial	mm	± 1						
Radial	mm	± 1						

Important: Retraction depth has to be strictly observed (Dimension B4)!

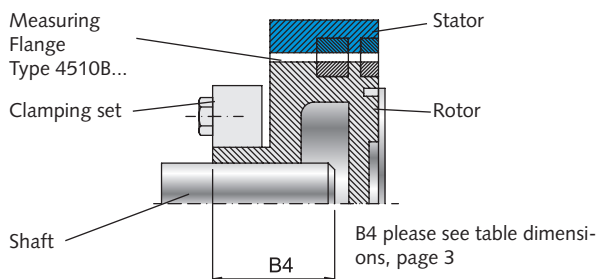


Fig. 5: Schematic diagram of the retraction depth

Application Examples

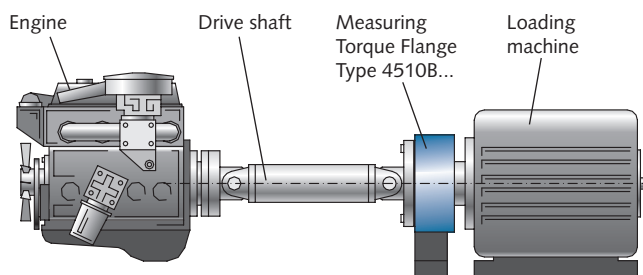


Fig. 6: Combustion engine front machine test stand

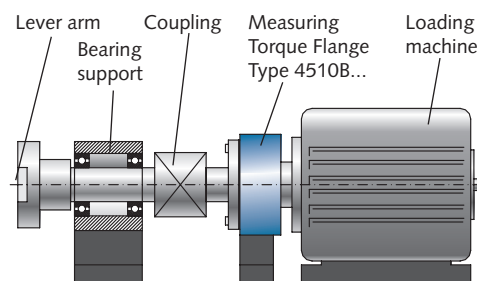


Fig. 7: Calibration facility

Mechanical Mounting

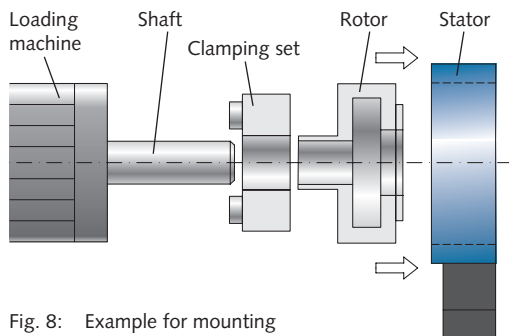


Fig. 8: Example for mounting

Included Accessories

- None

Optional Accessories

- Connection cable, length 5 m
Type/Art. No. KSM007203
- Connection cable, length 5 m,
12 pin – open ends
Type/Art. No. KSM124970-5
- Connection cable, length 5 m,
7 pin – open ends
Type/Art. No. KSM219710-5
- Connection cable, length 2,5 m,
12 pin – CoMo Torque
Type/Art. No. KSM186420-2,5
- Female connector 7 pin (plug C)
Type/Art. No. KSM000517
- Female connector 8 pin (plug D)
Type/Art. No. KSM013136
- ControlMonitor CoMo Torque
Type/Art. No. 4700A...
- Evaluation instrument for torque sensors
Type/Art. No. 4706A...
- Adapter flanges (on request)
- Couplings (on request)
- SensorTool

Our torque calibration service lab DKD-K-37701 offers traceable recalibration of any brands.

For further information of cable and connector see data sheet 000-615.

Ordering Key

Measuring Ranges in N·m

100	Size 1	100
200	Size 1	200
500	Size 2	500
1 000	Size 2	1K2
1 000	Size 3	1K3
2 000	Size 3	2K
4 000	Size 3	4K

Range Selection

Without	A0
Dual range sensor, rated torque 1:10 (Measuring range selection)	A1
Dual range sensor, rated torque 1:5 (Measuring range selection)	A2

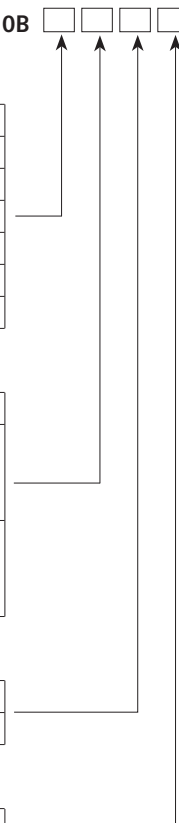
Output Signal

Analog output ± 10 VDC	B1
Frequency output 100 ± 40 kHz	B2

Increased Accuracy

Without	0
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Type 4510B



Order Example:

Type 4510B100A0B10

Measuring torque flange: Rated torque **100** N·m, without range selection: **A0**, Analog output ± 10 VDC: **B1**, without increased accuracy: **0**