

## measure. analyze. innovate.

# **Quattro Jump**

## **Portable Force Plate System**

Leg performance is a determinant factor for success in most sports. A mixture of explosive force, endurance and coordination is trained and very carefully optimized for each particular sports type.

Quattro Jump provides an objective measurement of force, power and jump height. A special protocol developed by Prof. Carmelo Bosco allows the quantification of leg performance.

- Objective measurement of jump force, jump height and jump power
- Immediate feedback to optimize the training program
- Rugged and accurate Kistler force plate technology. Portable thanks to lightweight sandwich design

#### Description

Quattro Jump consists of a portable Kistler force plate on which different jump types are performed. The force plate measures the vertical jump force which is analyzed with the computer connected to the system.

Kistler force plates are a worldwide standard in biomechanics and sports science since 40 years.

## Requirements for the PC

- Operating System: Windows® XP, Windows® Vista or Windows® 7
- Acrobat® Reader® for reading the PDF Instruction Manual
- Intel Pentium 4 class processor (1 GHz or higher recommended)
- 2 GB of RAM minimum
- Video display set to at least 800x600, 256 colors, small fonts selected
- Disk (free) space required: 125 MB in the target directory for data storage and software installation
- Microsoft compatible mouse
- Windows® Installer version 1.1 or later
- One (1) direct serial port (RS-232C) or USB to serial port adapter
- A color printer is recommended for creating hard copies of graphs

Type 9290BD



#### Technical Data

| Dimensions of the force plate |    | mm    | 920x920x125 |
|-------------------------------|----|-------|-------------|
| Range                         | Fz | kN    | 0 10        |
| Overload                      | Fz | kN    | 15          |
| Linearity                     |    | %FSO  | <±0,5       |
| Hysteresis                    |    | %FSO  | <1          |
| Natural Frequency             |    | Hz    | ≈150        |
| Operating temperature range   |    | ° C   | 0 50        |
| Weight                        |    | kg    | 21,6        |
| Sampling rate                 |    | Hz    | 500         |
| Resolution                    |    |       |             |
| Range 1                       |    | N/bit | 1           |
| Range 2                       |    | N/bit | 0,2         |
| Interface to the computer     |    |       |             |
| Connector type                |    |       | USB         |
| Power supply via USB          |    | V     | 5           |

Conforms with the provisions of directive 86/336/EG in accordance with the CE Declaration of Conformity.

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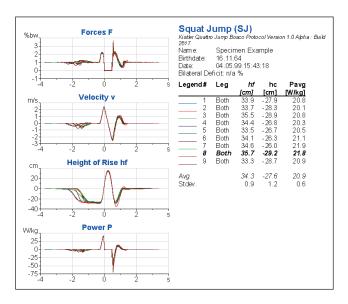


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#### **Quattro Jump Software**

The Quattro Jump Software is dedicated for routine jump performance measurement. It is therefore very easy to use. After every jump the protocol on the right side of the screen is updated. The best jump is highlighted.

The control area on the left side of the screen allows the user to delete or temporarily hide jumps from the protocol.



#### **Bosco Test**

The Bosco Protocol evaluates different types of «Squat Jump», «Countermovement Jump» and «Continuous Jump»:

| Des.   | Type of jump | No.  | Description                |
|--------|--------------|------|----------------------------|
| SJ     | Squat Jump   | 3 *  | Single jump starting from  |
|        |              |      | knees bent at 90 degrees   |
| SJbw   | Squat Jump + | 3 *  | Squat jump with additio-   |
|        | Body Weight  |      | nal load of up to one      |
|        |              |      | body weight                |
| CMJ    | Counter-     | 3 *  | Single jump starting with  |
|        | movement     |      | straight legs with a natu- |
|        | Jump         |      | ral flexion before takeoff |
| CJbref | Continuous   | 5*   | Series of jumps with bent  |
|        | Jump Bent    |      | knees, used as reference   |
|        | Legs Ref.    |      | to compare with CJb        |
|        |              |      | (15 60 s)                  |
| CJs    | Cont. Jump   | 5*   | Series of jumps with       |
|        | straight leg |      | straight knees             |
| CJb    | Cont. Jump   | 15   | Series of 15 60 s          |
|        | Bent Legs    | 60 s | jumping with bent knees    |

\* Recommended No. of jumps

## **Important Parameters**

| Force time curve                                     | F(t) |
|--|------|
| Jump height (rise of center of gravity)              | hf   |
| Depth of countermovement                             |      |
| Average Power  | Pavg |
| % Fast Twitch Fibers (estimate)                      | %FT  |
| Force at the transition from eccentric to concentric | Fi   |
| Bosco Index  |      |

Leg Equilibrium Index

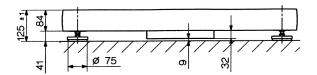
Speed/Endurance Index

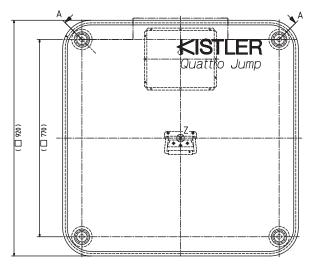
Effect of Prestretch

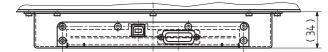
**Fatigue Parameters** 

approximately 70 further Parameters

#### **Dimensions**







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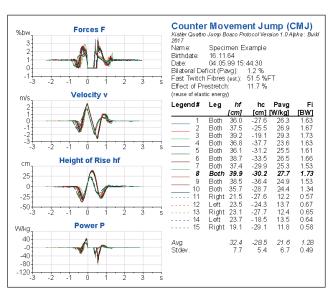


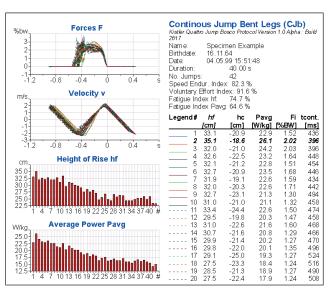
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## **Jump Type Specific Bosco Protocols**

For each jump type a variety of parameters is calculated and presented in a jump type specific protocol. This protocol can be customized by the user.

## **Examples:**





#### **Summary Protocol**

A summary protocol (also customizable) combines the most important parameters of an entire test. It also allows the comparison of different tests for instance within a team or over a certain time.

| Squa<br>#      | t Jumps (SJ and SJb)<br>Name | <i>N)</i><br>Date     | hf SJ<br>[cm]               | hf SJbw<br>[cm]                  | Bosco Ind.                |                              |                                |                   |
|----------------|------------------------------|-----------------------|-----------------------------|----------------------------------|---------------------------|------------------------------|--------------------------------|-------------------|
| 1              | Example, Specimen            | 04.05.99              | ↑ 35.7                      | 24.3                             | 68.1                      |                              |                                |                   |
| 4vg.<br>Stdev. |                              |                       | 35.7<br>0.0                 | 24.3<br>0.0                      | 68.1<br>0.0               |                              |                                |                   |
| Coun           | ntermovement Jump (          | C <i>INU)</i><br>Date | hf<br>(cm)                  | Fi<br>I%BWI                      | Pavg<br>(Wkg)             | Effect of<br>Prestretch      | Fast Twitch<br>Fibres<br>[%FT] |                   |
|                | Example, Specimen            | 04.05.99              | 39.9                        | 1.73                             | 27.7                      | 11.7                         | 51.5                           |                   |
| 4vg.<br>Stdev. |                              |                       | 39.9<br>0.0                 | 1.73<br>0.00                     | 27.7<br>0.0               | 11.7<br>0.0                  | 51.5<br>0.0                    |                   |
| Cont           | inuous Jump (CJs an          | d CJbref)             |                             | CJs                              |                           | 1                            | CJbref                         |                   |
| #              | Name                         | Date                  | hf<br>(cm)                  | Pavg<br>[Wkq]                    | k<br>[kN/m]               | hf<br>(cm)                   | Pavg<br>(Wkg)                  | Leg Equ.<br>Index |
| ı              | Example, Specimen            | 04.05.99              | 29.7                        | 34.5                             | 29.75                     | 38.9                         | 24.2                           | 1.4               |
| 4vg.<br>Stdev. |                              |                       | 29.7<br>0.0                 | 34.5<br>0.0                      | 29.75<br>0.00             | 38.9<br>0.0                  | 24.2<br>0.0                    | 1.4<br>0.0        |
| Cont           | inuous Jump (CJb)            |                       |                             | CJI                              | Overview                  |                              | CJb 0                          | 15s               |
| ¥              | Name                         | Date                  | Speed<br>Endur.<br>Ind. [%] | Voluntary<br>Effort<br>Index [%] | Fatigue<br>Index<br>hf[%] | Fatigue<br>Index<br>Pavg [%] | hf<br>[cm]                     | Pavg<br>[₩kg]     |
| 1              | Example, Specimen            | 04.05.99              | 82.3                        | 91.6                             | 74.7                      | 64.6                         | 32.0                           | 22.4              |

#### **Included Accessories**

• Quattro Jump Software

• USB cable type A – type B

## Type/Art. No.

2822A-01-0 55066002

### **Optional Accessories**

none

## **Ordering Code**

• Quattro Jump Portable force plate system Type 9290BD

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